## LECTURE 5

ABSTRACT. Phase curves and commutators of vector fields.

1. Phase curves of a vector field. A curve  $\gamma : \mathbb{R} \to M$  on a smooth manifold M is called an phase curve of a vector field Z if  $\gamma'(t) = Z(\gamma(t))$  for all  $t \in \mathbb{R}$ . One can also consider phase curves defined on open subsets of  $\mathbb{R}$ , say, segments (a, b).

**Theorem 1.** Let M be a manifold and Z, a smooth vector field on it. Then for any  $a \in M$  there exists an open subset  $U \subset M$ ,  $a \in U$ , and a number  $\varepsilon > 0$  such that for any  $b \in U$  there exists a unique phase curve  $\gamma_b : (-\varepsilon, \varepsilon) \to M$  of the vector field Z such that  $\gamma_b(0) = b$ . The map  $\Gamma : U \times (-\varepsilon, \varepsilon) \to M$  given by a formula  $\Gamma(b, t) \stackrel{def}{=} \gamma_b(t)$  is smooth.

Uniqueness in this theorem means that if  $\gamma_1 : (-\varepsilon_1, \varepsilon_1) \to M$  and  $\gamma_2 : (-\varepsilon_2, \varepsilon_2) \to M$  are phase curves with  $\gamma_1(0) = \gamma_2(0)$  then they coincide where they both are defined, that is,  $\gamma_1(t) = \gamma_2(t)$  for any  $t \in (-\varepsilon_1, \varepsilon_1) \cap (-\varepsilon_2, \varepsilon_2)$ .

*Proof.* Since it is a local statement, one can suppose that  $M = \mathbb{R}^n$ . Then the vector field Z is  $Z(x) = \sum_{i=1}^n z_i(x_1, \dots, x_n) \frac{\partial}{\partial x_i}$ .

and the curve  $\gamma(t) \stackrel{\text{def}}{=} (\gamma_1(t), \dots, \gamma_n(t))$  is its phase curve if the functions  $\gamma_1(t), \dots, \gamma_n(t)$  are solutions of the system of ordinary differential equations (ODE)  $\frac{d}{dt}\gamma_i(t) = z_i(\gamma_1(t), \dots, \gamma_n(t)), i = 1, \dots, n$ . The theorem follows now from the existnce and uniqueness theorem for systems of the first-order ODE.

If M is compact, the situation becomes global:

**Theorem 2.** Let M be a compact manifold and Z, a smooth vector field on it. Then there exists a smooth map  $\Gamma: M \times \mathbb{R} \to M$  (called a phase flow of the vector field Z) such that

- (1)  $\Phi(a,0) = a$  for all  $a \in M$ .
- (2)  $\Phi(\Phi(a, t_1), t_2) = \Phi(a, t_1 + t_2)$  for all  $a \in M$  and  $t_1, t_2 \in \mathbb{R}$ .
- (3)  $\frac{d\Phi(a,t)}{dt}\Big|_{t=0} = Z(\Phi(a,\tau)).$

Taking  $t_1 = t$  and  $t_2 = -t$  in Property 2, one obtains  $\Phi(\Phi(a, t), -t) = \Phi(a, 0) = a$  (from Property 1). Thus, for any fixed  $t \in \mathbb{R}$  the map  $\Phi_t : M \to M$  defined by  $\Phi_t(a) = \Phi(a, t)$  is a diffeomorphism (it is smooth because  $\Phi$  is smooth and its inverse is  $\Phi_{-t}$ , which is also smooth). Thus, Properties 1 and 2 (known together as 1-parametric group property) can be expressed by saying that  $t \mapsto \Phi_t$  is a homomorphism from the additive group  $\mathbb{R}$  (the operation is addition of numbers) to the group of diffeomorphisms of the manifold M (the operation is composition of maps).

Proof of Theorem 2. Take for every  $a \in M$  an open set  $U_a \subset M$  and a number  $\varepsilon_a > 0$  as in Theorem 1. By the compactness of M there exist points  $a_1, \ldots, a_N \in M$  such that  $M = U_{a_1} \cup \cdots \cup M_{a_N}$ ; take  $\varepsilon \stackrel{\text{def}}{=} \min(\varepsilon_{a_1}, \ldots, \varepsilon_{a_N}) > 0$ . Then for any point  $a \in M$  there exists (and is unique) a phase curve  $\gamma_a : (-\varepsilon, \varepsilon) \to M$  with  $\gamma(0) = a$ . For any  $s \in (-\varepsilon, \varepsilon)$  the curve  $\gamma_{a,s}(t) \stackrel{\text{def}}{=} \gamma_a(t+s)$  is a phase curve of Z defined on an interval  $(-\varepsilon + s, \varepsilon - s)$  and such that  $\gamma_{a,s}(0) = \gamma_a(s)$ . Due to uniqueness,  $\gamma_{a,s}(t) = \gamma_{\gamma_a(s)}(t)$  for all possible t. This allows to extend  $\gamma_a$  to the smooth curve  $(-\varepsilon, 3\varepsilon/2) \to M$  (to be called still  $\gamma_a$  saying that  $\gamma_a(t)$  is defined as it previously was for  $|t| < \varepsilon$  and  $\gamma_a(t) \stackrel{\text{def}}{=} \gamma_{\gamma_a(\varepsilon/2)}(t-\varepsilon/2)$  if  $\varepsilon/2 < |t| < 3\varepsilon/2$ ; the curve obtained is again an phase curve of Z. In a similar manner one may extend  $\gamma_a$  to an phase curve  $(-3\varepsilon/2, 3\varepsilon/2) \to M$ , etc., proving eventually that for any  $a \in M$  there exists a unique phase curve  $\gamma_a : \mathbb{R} \to M$  of the vector field Z.

Define now  $\Phi(a, t) \stackrel{\text{def}}{=} \gamma_a(t)$ . Property 1 is obvious; Property 3 expresses the fact that  $\gamma_a$  is a phase curve. Property 2 follows from uniquenes of the phase curve by the trick already used in the previous paragraph: for any fixed  $t_1$  the curve  $\delta(t) \stackrel{\text{def}}{=} \Phi(a, t_1 + t)$  is a phase curve of Z with  $\delta(0) = \Phi(a, t_1)$ . By uniqueness,  $\delta(t) = \Phi(\Phi(a, t_1), t)$  for any t; take  $t = t_2$ .

*Example* 1. A phase curve of the vector field  $\frac{\partial}{\partial x_1}$  on  $\mathbb{R}^n$  passing through a point  $a = (a_1, \ldots, a_n)$  is  $\gamma_a(t) = (a_1 + t, a_2, \ldots, a_n)$ ; it is defined for all  $t \in \mathbb{R}$ . An phase curve of the vector field  $x_1 \frac{\partial}{\partial x_1} + \cdots + x_n \frac{\partial}{\partial x_n}$  passing through a point a is  $\gamma_a(t) = ae^t$ ,  $t \in \mathbb{R}$ .

*Example 2.* Phase curves of the vector field  $x\frac{\partial}{\partial y} - y\frac{\partial}{\partial x}$  on  $\mathbb{R}^2$  are  $\gamma(t) = r(\cos(t+\varphi), \sin(t+\varphi))$  for all  $t \ge 0$  and  $\varphi \in \mathbb{R}$ . They are defined for all  $t \in \mathbb{R}$ .

*Example* 3. A phase curve of the vector field  $t^2 \frac{d}{dt}$  passing through a point  $a \in \mathbb{R}$  is  $\gamma_a(t) = \frac{a}{1-at}$ . These curves (except  $\gamma_0 \equiv 0$ ) are defined on infinite segments:  $t \in (-\infty, 1/a)$  for a > 0 and  $t = (1/a, +\infty)$  for a < 0. So, there is no  $\varepsilon > 0$  such that all  $\gamma_a$  are defined on  $(-\varepsilon, \varepsilon)$ . For any segment  $(p, q) \subset \mathbb{R}$ , though, there exists such  $\varepsilon$  that  $\gamma_a$  for all  $a \in (p, q)$  are defined on  $(-\varepsilon, \varepsilon)$  (this is a particular case of Theorem 1).

## 2. Commutator of vector fields.

**Theorem 3.** Let  $A, B : X \to X$  be derivations of an associative commutative algebra X. Then the commutator  $C \stackrel{\text{def}}{=} [A, B] \stackrel{\text{def}}{=} A \circ B - B \circ A$  is also a derivation ( $\circ$  meaning composition of maps).

Proof. The map C is apparently linear; take now  $f, g \in X$ , so C(fg) = A(B(fg)) - B(A(fg)) = A(fB(g) + B(f)g) - B(fA(g) + A(f)g) = A(f)B(g) + fA(B(g)) + A(B(f))g + B(f)A(g) - B(f)A(g) - f(B(A(g)) - B(A(f))g - A(f)B(g) = fC(g) + C(f)g.

## Corollary 1. A commutator of two vector fields on a manifold M is a vector field.

Here vector fields are considered as derivations of the algebra  $C^{\infty}(M)$  of smooth functions on M. In coordinates  $x = (x_1, \ldots, x_n)$  if  $A = \sum_{i=1}^n a_i(x) \frac{\partial}{\partial x_i}$  and  $B = \sum_{i=1}^n b_i(x) \frac{\partial}{\partial x_i}$  then for any function  $f \in C^{\infty}(M)$  one has

$$[A,B](f) = A(\sum_{i=1}^{n} b_i(x)\frac{\partial f}{\partial x_i}) - B(\sum_{i=1}^{n} a_i(x)\frac{\partial f}{\partial x_i}) = \sum_{i,j=1}^{n} a_j(x)\frac{\partial b_i(x)}{\partial x_j}\frac{\partial f}{\partial x_i} - \sum_{i,j=1}^{n} b_j(x)\frac{\partial a_i(x)}{\partial x_j}\frac{\partial f}{\partial x_i} + \text{terms containing } \frac{\partial^2 f}{\partial x_i \partial x_j} \text{ that have to cancel by Corollary 1.}$$

So, in coordinates  $[A, B] = \sum_{i=1}^{n} \left( \sum_{j=1}^{n} a_j(x) \frac{\partial b_i(x)}{\partial x_j} - b_j(x) \frac{\partial a_i(x)}{\partial x_j} \right) \frac{\partial}{\partial x_i}$ . We are going now to give a geometric description of the commutator of vector fields. Take a point  $a \in M$  and

We are going now to give a geometric description of the commutator of vector fields. Take a point  $a \in M$  and let  $\gamma_a : (-\varepsilon, \varepsilon) \to M$  be an phase curve of the field A with  $\gamma_a(0) = a$ ; take  $P_t \stackrel{\text{def}}{=} \gamma_a(t)$  for any  $t \in (-\varepsilon, \varepsilon)$ . Let  $\delta_{P_t} : (-\varepsilon, \varepsilon) \to M$  be an phase curve of the vector field B with  $\delta_{P_t}(0) = P_t$ ; take  $Q_{t,s} \stackrel{\text{def}}{=} \delta_{P_t}(s)$  for any  $s \in (-\varepsilon, \varepsilon)$ . Then let  $\gamma_{Q_{t,s}} : (-\varepsilon, \varepsilon) \to M$  be an phase curve of A with  $\gamma_{Q_{t,s}}(0) = Q_{t,s}$ ; take  $R_{t,s} \stackrel{\text{def}}{=} \gamma_{Q_{t,s}}(-t)$  (the same tas before!). Finally, let  $\delta_{R_{t,s}} : (-\varepsilon, \varepsilon) \to M$  be an phase curve of the vector field B with  $\delta_{R_{t,s}}(0) = R_{t,s}$ ; take  $U(t,s) \stackrel{\text{def}}{=} \delta_{R_{t,s}}(-s)$ .

Now  $U: (-\varepsilon, \varepsilon)^2 \to M$  is a smooth map; by uniqueness of an phase curve one has U(t, 0) = U(0, s) = a for all  $t, s \in (-\varepsilon, \varepsilon)$ . Fix  $s \in (-\varepsilon, \varepsilon)$ ; then the formula  $\lambda_s(t) \stackrel{\text{def}}{=} U(t, s)$  defines a smooth curve  $\lambda_s : (-\varepsilon, \varepsilon) \to M$  with  $\lambda_s(0) = a$ . The equivalence class of the curve  $\lambda_s$  at a is a vector  $\ell(s) \in T_aM$ ; so  $\ell: (-\varepsilon, \varepsilon) \to T_aM$  is a smooth map.

**Theorem 4.**  $\ell'(0) = [A, B](a)$ .

*Proof.* To compute  $\ell'(0)$  it is enough to operate with  $\ell(s)$  for  $s \in (-\varepsilon, \varepsilon)$  with  $\varepsilon > 0$  arbitrarily small; to define such  $\ell(s)$  one has to know U(t,s) for  $t, s \in (-\varepsilon, \varepsilon)$ . So, the statement has local nature, and it is enough to prove it for  $M = \mathbb{R}^n$  and a = 0.

Consider the Taylor's formula for the map U:  $U(t,s) = u_{00} + u_{10}t + u_{01}s + u_{11}ts + o(t) + o(s)$ ,  $t, s \to 0$  (pay attention that the last two terms depend on both t and s!). Since U(t,0) = U(0,s) = 0, one has  $u_{00} = u_{10} = u_{01} = 0$ , and the last two terms are divisible by ts. Thus the curve  $\lambda_s(t) = u_{11}ts + so(t) + to(s)$ , hence  $\ell(s) = \lambda'_s(0) = u_{11}s + o(s)$ , and  $\ell'(0) = u_{11}$ . So, to prove the theorem it suffices to compute  $u_{11}$ .

Remember that  $A(x) = (a_1(x), \ldots, a_n(x))$  and  $B(x) = (b_1(x), \ldots, b_n(x))$ . So,  $P_t = (a_1(0)t, \ldots, a_n(0)t) + o(t)$ . The term o(t) cannot contribute to the term  $u_{11}ts$  in the formula for U(t, s) (explain why!), so we will write simply

$$\begin{split} P_t &= (a_1(0)t, \dots, a_n(0)t) + \dots, \text{ and will be using } \dots \text{ to denote all such "uninteresting" terms. Now} \\ Q_{t,s} &= P_t + (b_1(P_t), \dots, b_n(P_t))s + \dots \\ &= (a_1(0)t + b_1(0)s + \frac{d}{d\tau}b_1(P_\tau)\Big|_{\tau=0} ts + \dots, \dots, a_n(0)t + b_n(0)s + \frac{d}{d\tau}b_n(P_\tau)\Big|_{\tau=0} ts + \dots) \\ &= (a_1(0)t + b_1(0)s + ts\sum_{j=1} a_j(0)\frac{\partial b_1}{\partial x_j}(0) + \dots, \dots, a_n(0)t + b_n(0)s + ts\sum_{j=1} a_j(0)\frac{\partial b_n}{\partial x_j}(0) + \dots), \\ R_{t,s} &= Q_{t,s} - (a_1(Q_{t,s}), \dots, a_n(Q_{t,s})t + \dots \\ &= Q_{t,s} - (a_1(0)t, \dots, a_n(0)t) - (\sum_{j=1}^n b_j(0)\frac{\partial a_1}{\partial x_j}(0)ts + \dots, \sum_{j=1}^n b_j(0)\frac{\partial a_n}{\partial x_j}(0) + \dots) \\ &= (b_1(0)s, \dots, b_n(0)s) + ts(\sum_{j=1}^n \left(a_j(0)\frac{\partial b_1}{\partial x_j}(0) - b_j(0)\frac{\partial a_1}{\partial x_j}(0)\right), \dots, \sum_{j=1}^n \left(a_j(0)\frac{\partial b_n}{\partial x_j}(0) - b_j(0)\frac{\partial a_n}{\partial x_j}(0)\right) + \dots, \\ U(t,s) &= R_{t,s} - s(b_1(R_{t,s}), \dots, b_n(R_{t,s})) + \dots = R_{t,s} - s(b_1(0), \dots, b_n(0)) + \dots \\ &= ts(\sum_{j=1}^n \left(a_j(0)\frac{\partial b_1}{\partial x_j}(0) - b_j(0)\frac{\partial a_1}{\partial x_j}(0)\right), \dots, \sum_{j=1}^n \left(a_j(0)\frac{\partial b_n}{\partial x_j}(0) - b_j(0)\frac{\partial a_n}{\partial x_j}(0)\right) + \dots, \\ \text{so the theorem is proved.} \Box$$

so the theorem is proved.

*Example* 4. A commutator of the vector fields  $Z = x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y}$  and  $W = x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x}$  on  $\mathbb{R}^2$  is 0. The corresponding phase flows are  $\Psi((x, y), t) = (xe^t, ye^t)$  and  $\Psi((x, y), s) = (x\cos s + y\sin s, -x\sin s + y\cos s)$  according to Examples 1 and 4. The flows  $\Phi$  and  $\Psi$  commute:  $\Phi(\Psi((x, y), s), t) = e^t(x\cos s + y\sin s, -x\sin s + y\cos s) = \Psi(\Phi((x, y), t), s)$ . Using the notation from the theorem, the map  $U(t, s) \equiv (x, y)$  (a constant map), so  $\ell(s) \equiv 0$ , confirming the theorem.